

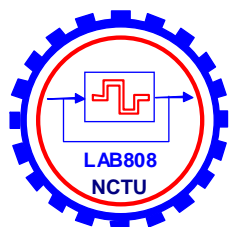
台灣新竹·交通大學·電機控制工程研究所·808實驗室
電源系統與晶片、數位電源、馬達控制驅動晶片、單晶片 DSP/FPGA 控制
Lab-808: Power Electronic Systems & Chips Lab., NCTU, Taiwan
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直流伺服驅動器的模擬~從系統到元件

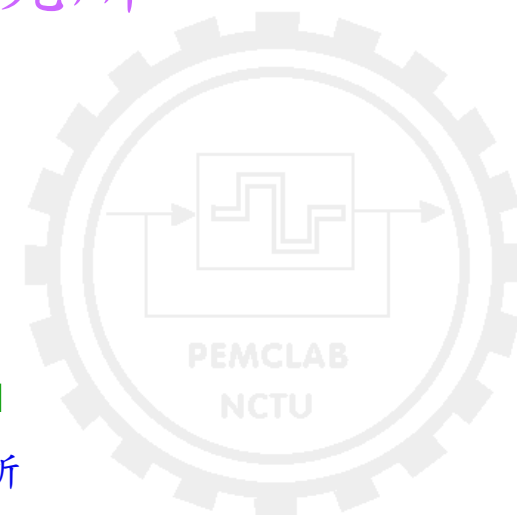
鄒應嶼 教授

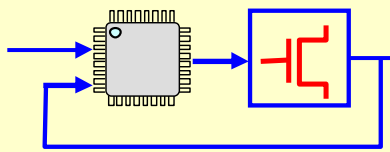
國立交通大學 電機控制工程研究所

2009年1月15日



Lab808: 電力電子系統與晶片實驗室
Power Electronics Systems & Chips, NCTU, TAIWAN
台灣新竹·交通大學·電機控制工程研究所

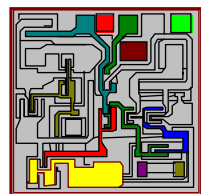




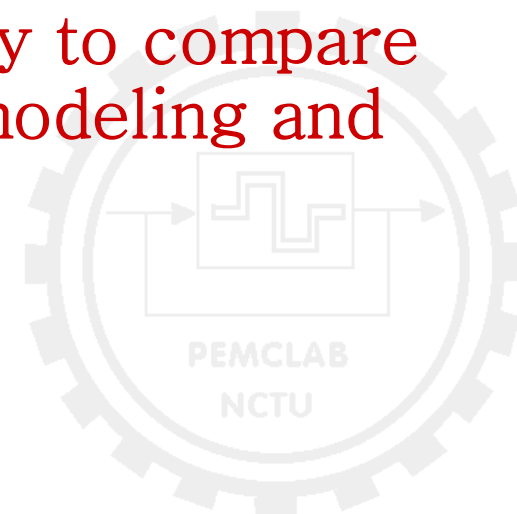
Why do we need to know the detailed characteristics of these basic components?



You may do experiment by try and error, or you can do experiment intuitively to compare with design-oriented analysis, modeling and simulation!

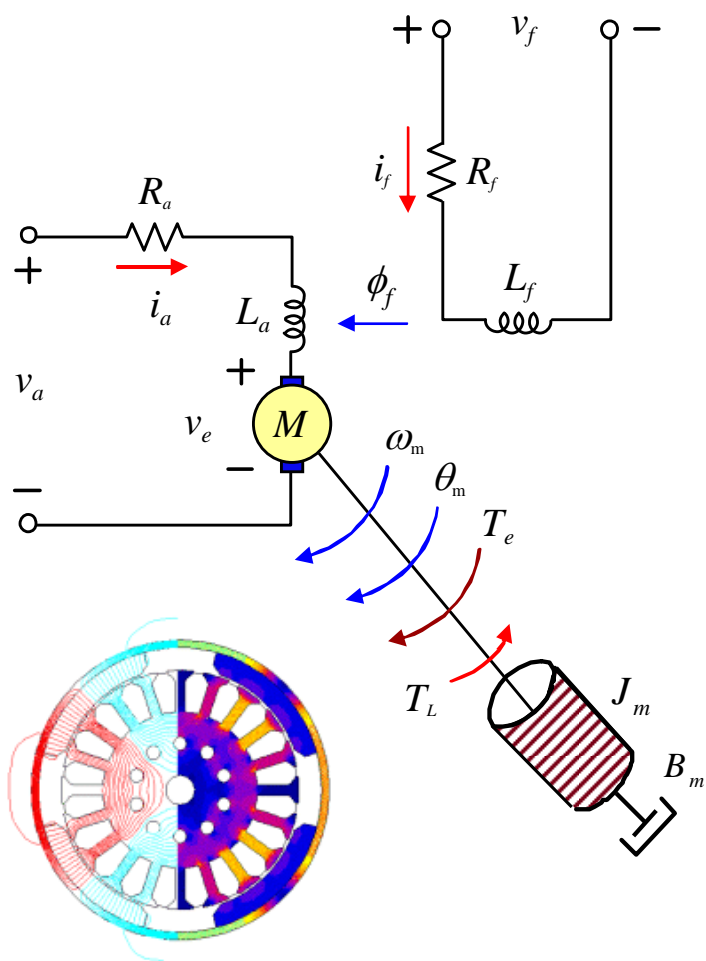


電力電子系統與晶片實驗室
Power Electronic Systems & Chips Lab.
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Modeling of a Separately Excited DC Motor

From Equivalent Circuit to Differential Equations



electrical equation:
$$v_a = i_a R_a + L_a \frac{di_a}{dt} + v_{emf}$$

$$v_f = i_f R_f + L_f \frac{di_f}{dt}$$

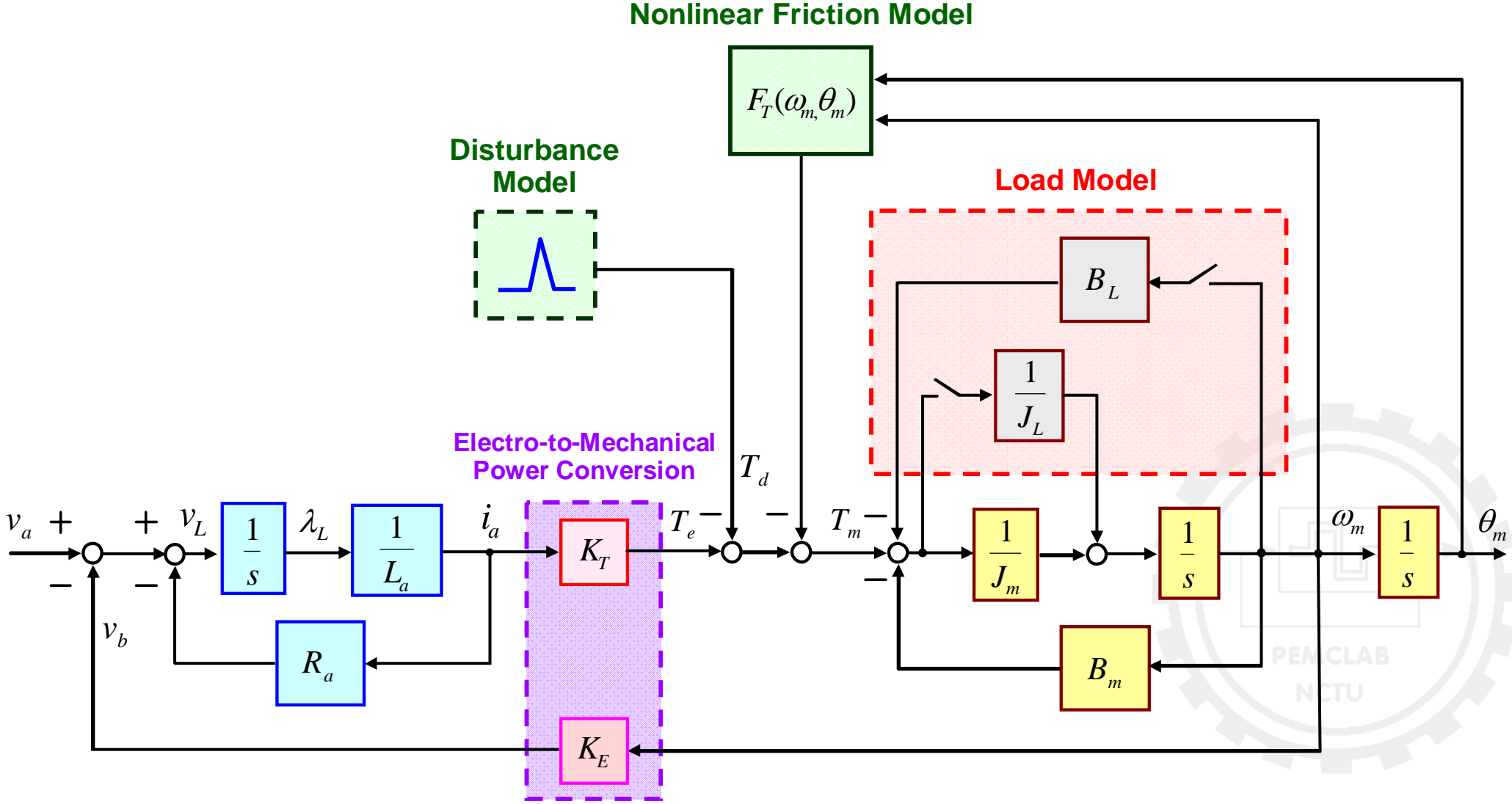
back *emf* equation:
$$v_{emf} = K_f \phi_f \omega_m$$

torque equation:
$$T_e = K_f \phi_f i_a$$

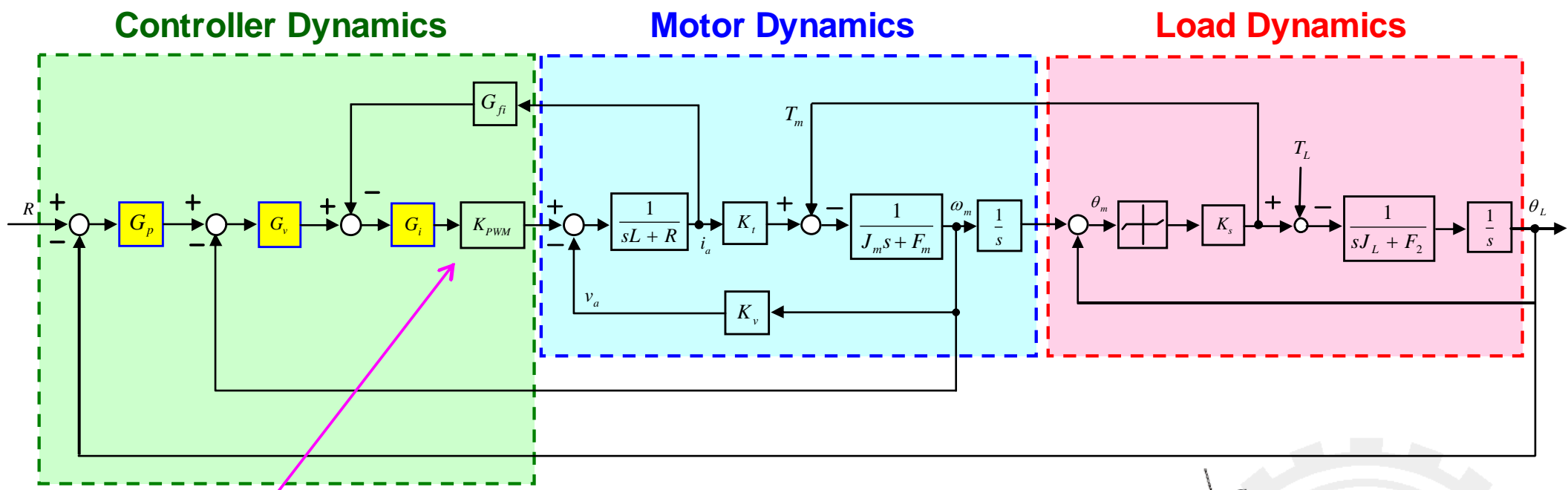
mechanical equation:
$$T_e = T_f + T_L + J_m \frac{d\omega_m}{dt} + B_m \omega_m$$

$$\omega_m = \frac{d\theta_m}{dt}$$

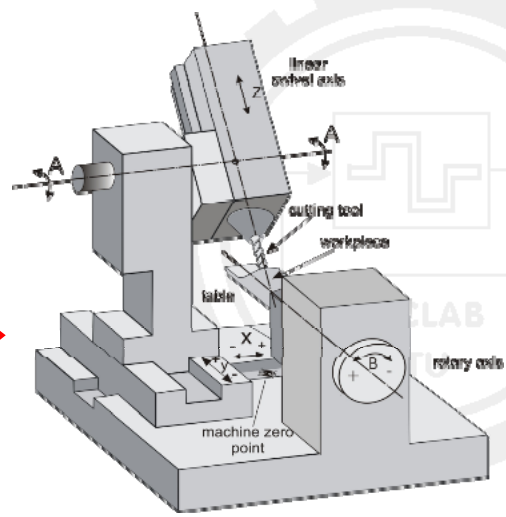
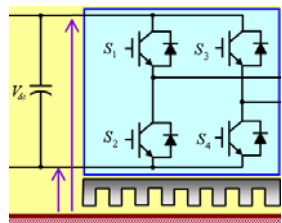
Block Diagram Representation of a PM DC Motor



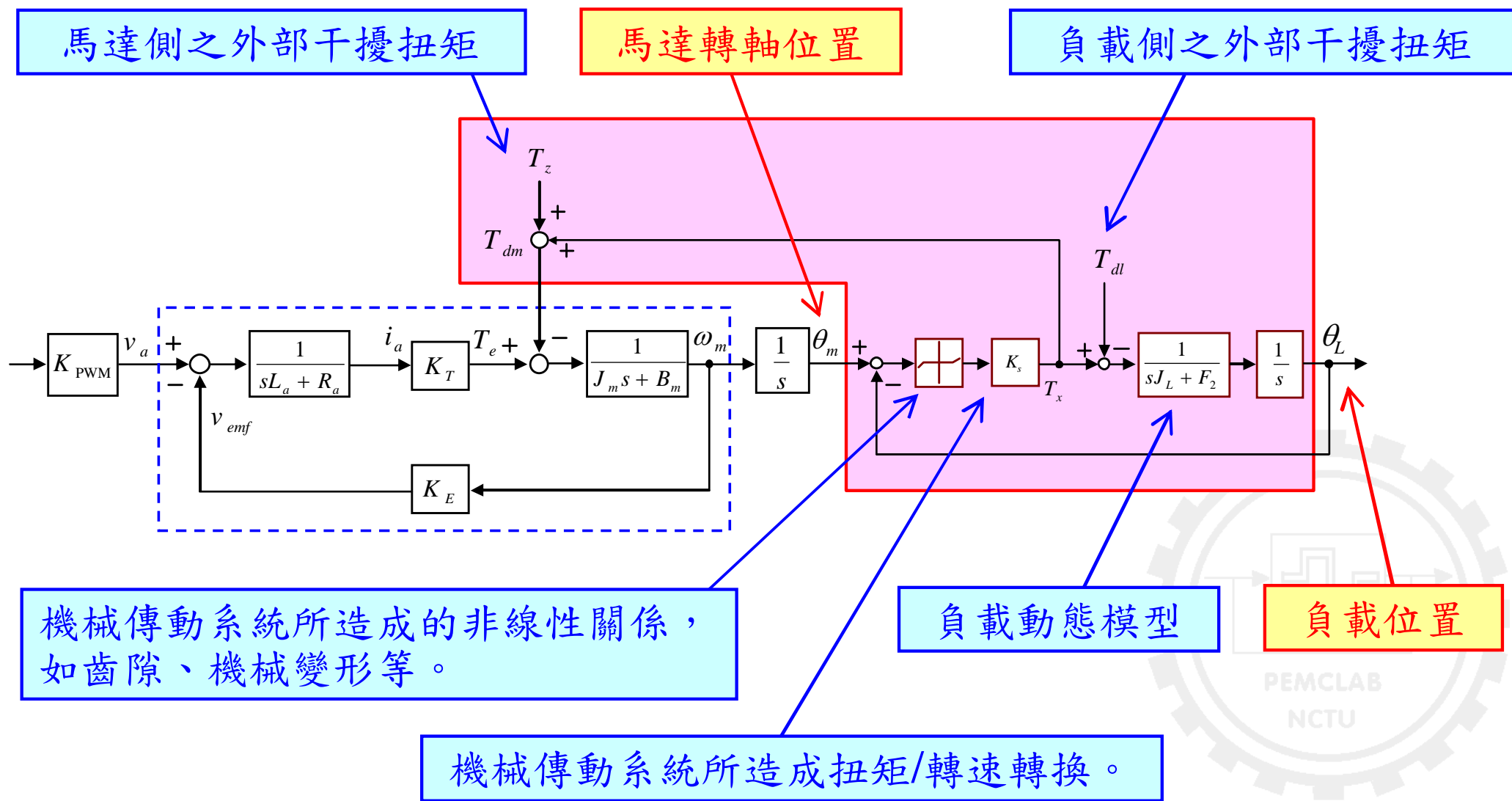
Modeling of a DC Servo Drive with Load Dynamics



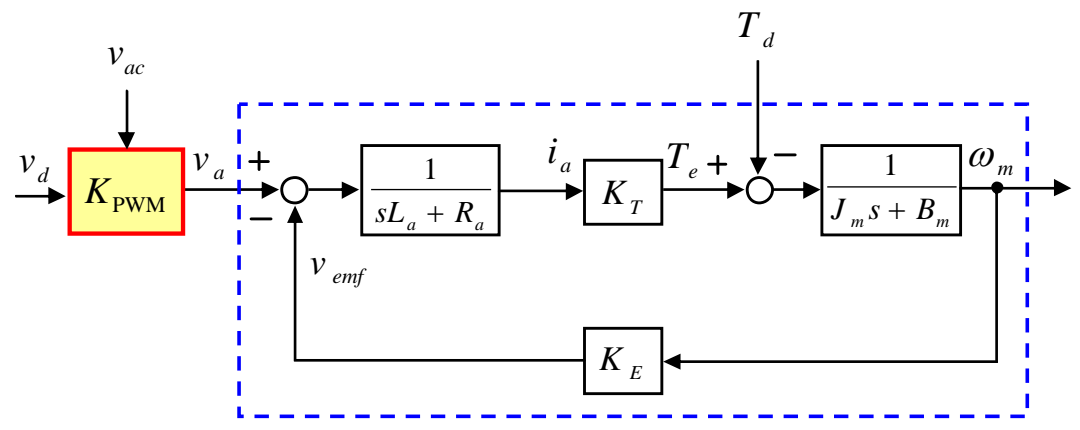
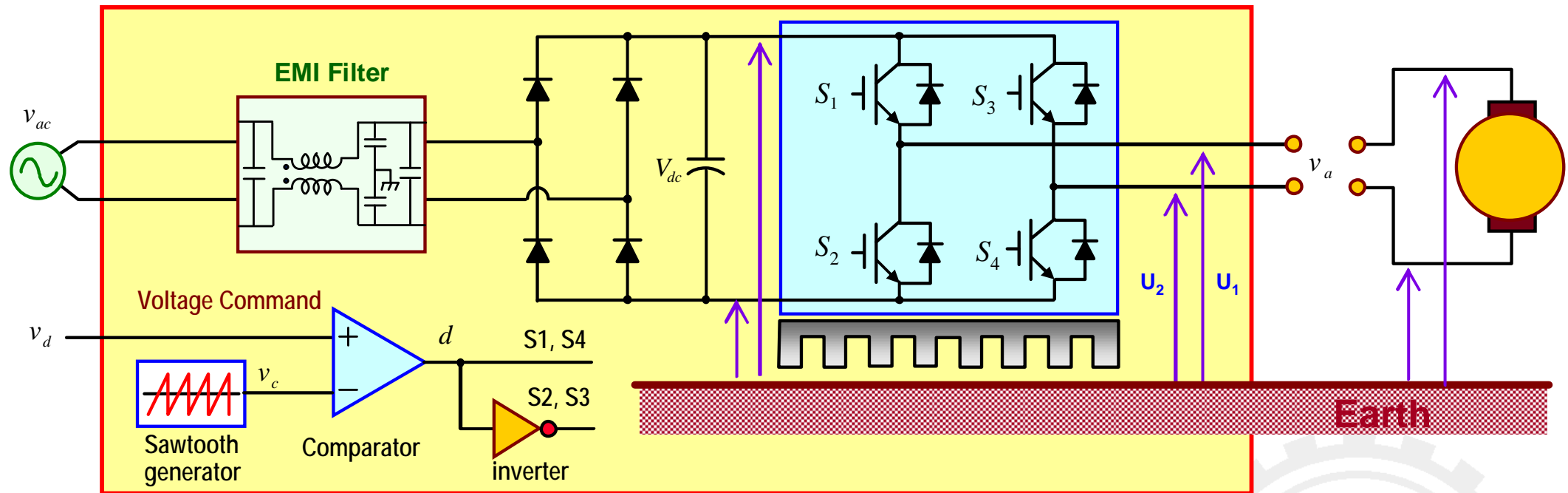
Nonlinearity of PWM Amp.



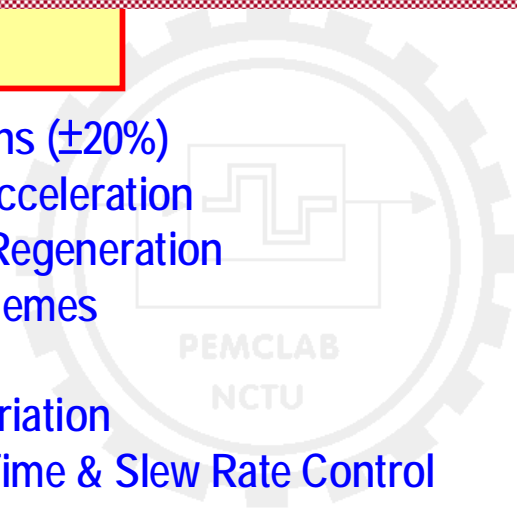
Modeling of Load Dynamics and Disturbances



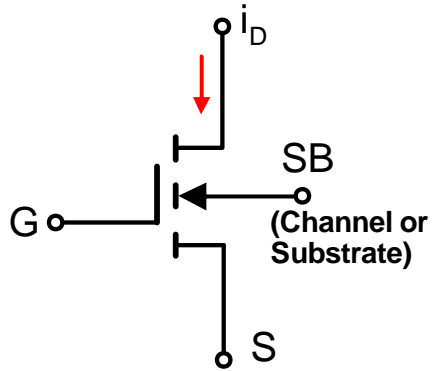
Modeling the PWM Amplifier



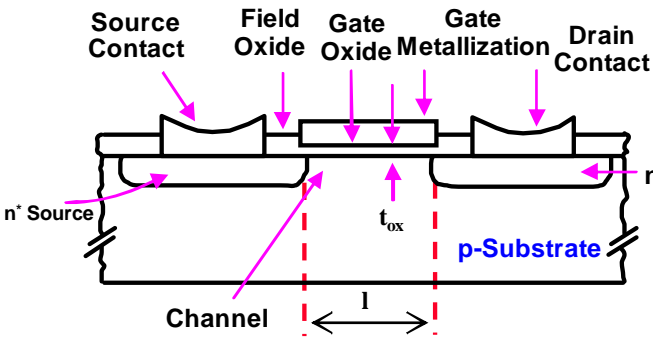
- Line Voltage Variations ($\pm 20\%$)
- Voltage Fall Due to Acceleration
- Voltage Rise Due to Regeneration
- PWM Modulation Schemes
- Dead-Time Effect
- Motor Parameters Variation
- Turn-On & Turn-Off Time & Slew Rate Control
- Common-Mode Noises



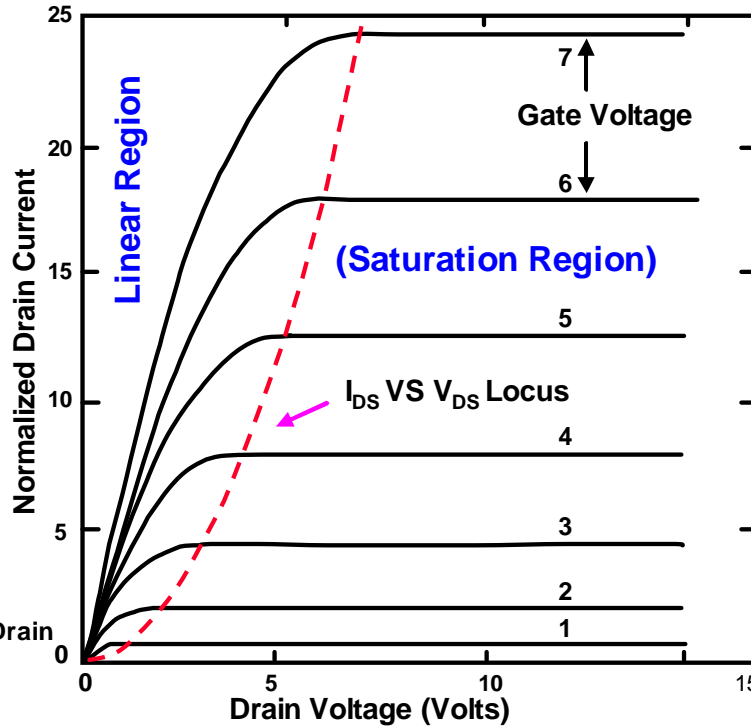
Characteristics of N-Channel MOSFET



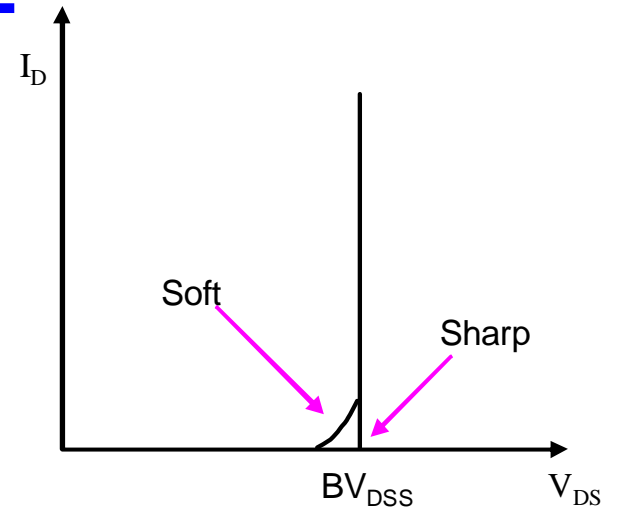
Symbol (N-Channel)



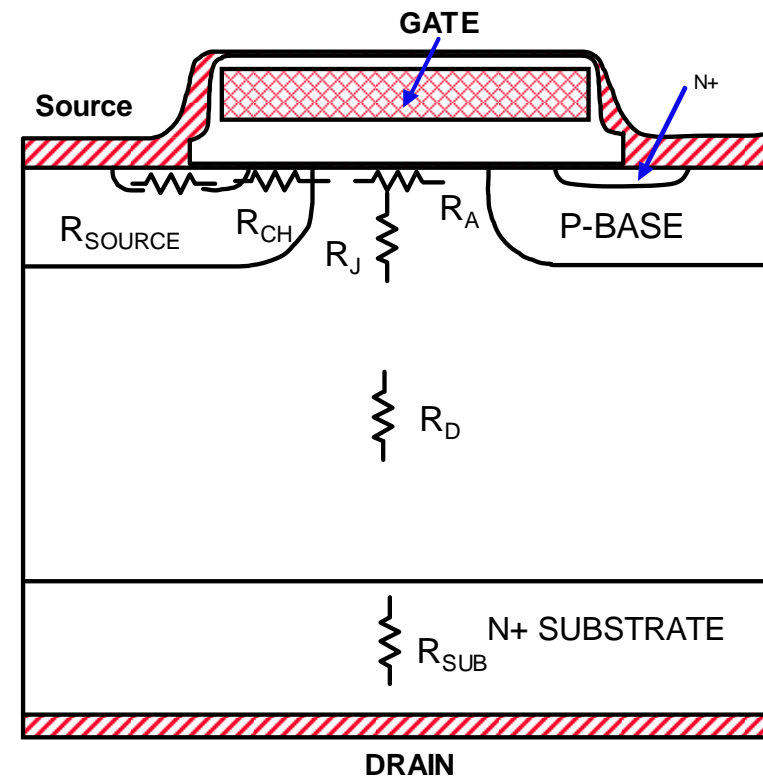
Schematic



Current-Voltage Characteristics

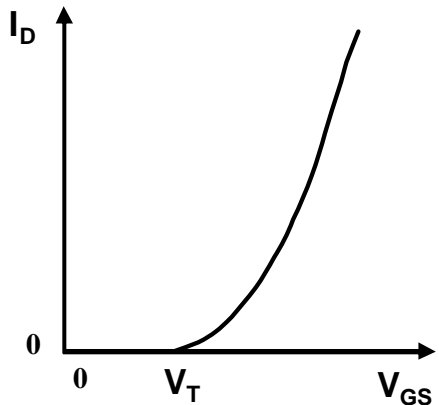


Breakdown Characteristics

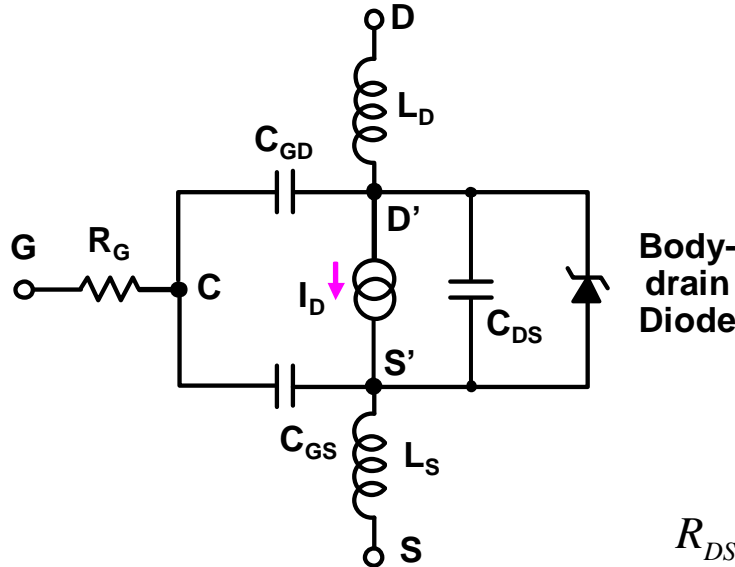


$$R_{DS(on)} = R_{source} + R_{ch} + R_A + R_J + R_D + R_{sub} + R_{wcmf}$$

Origin of Internal Resistance



Transfer Characteristics

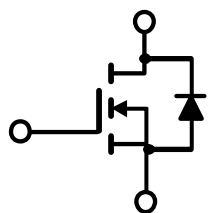


Equivalent circuit

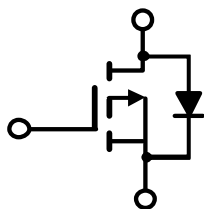
MOSFET Device Model (PSIM)

Linear switches, which can operate in three states, include npn and pnp BJT, and n-channel and p-channel MOSFET. BJT devices can operate in either cut-off, linear, or saturation state. MOSFET devices can operate in either cut-off, active, or ohmic state.

MOSFET
(n-channel)

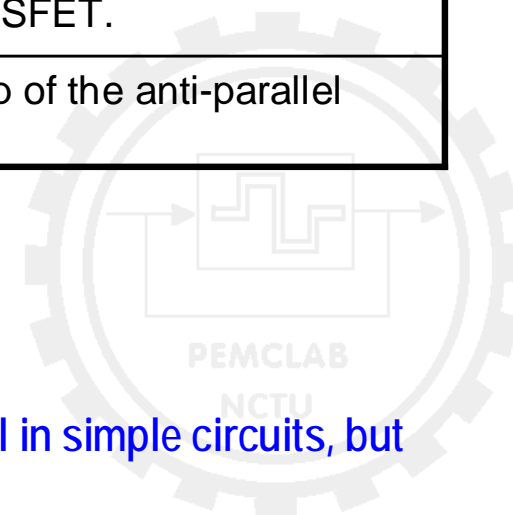


MOSFET
(p-channel)



Parameters	Descriptions
On Resistance	On resistance $R_{ds(on)}$ of the MOSFET, in Ohm.
Threshold Voltage $V_{gs(th)}$	Threshold voltage of the gate-to-source voltage, in V, beyond which the MOSFET starts to conduct.
Transconductance g_m	Transconductance g_m of the MOSFET.
Diode Voltage Drop	Forward conduction voltage drop of the anti-parallel diode, in V.

Warning: It has been found that linear switch models for BJT and MOSFET work well in simple circuits, but may not work in complex circuits. Please use these models with caution.



MOSFET Device Model (PSPICE)

General form

M<name> <drain node> <gate node> <source node>
+ <bulk/substrate node> <model name>
+ [L=<value>] [W=<value>]
+ [AD=<value>] [AS=<value>]
+ [PD=<value>] [PS=<value>]
+ [NRD=<value>] [NRS=<value>]
+ [NRG=<value>] [NRB=<value>]
+ [M=<value>] [N=<value>]

Examples

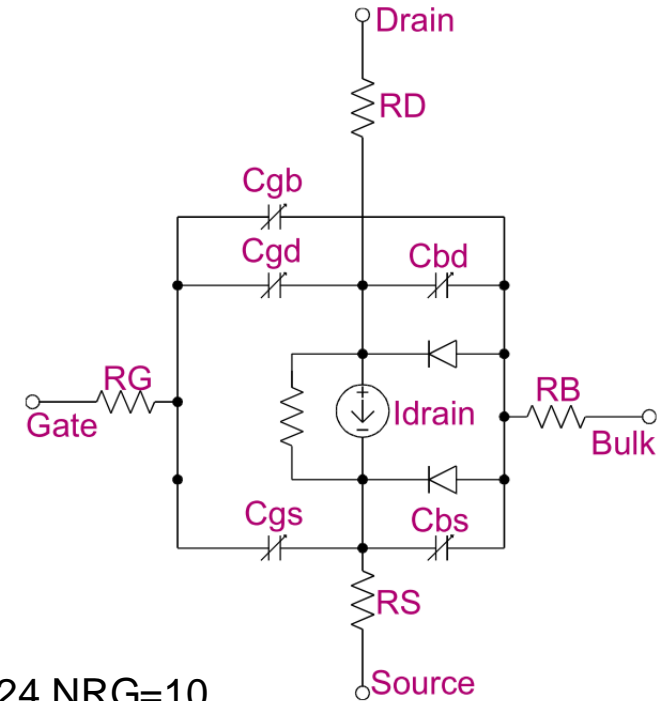
```
M1 14 2 13 0 PNOM L=25u W=12u
M13 15 3 0 0 PSTRONG
M16 17 3 0 0 PSTRONG M=2
M28 0 2 100 100 NWEAK L=33u W=12u
+ AD=288p AS=288p PD=60u PS=60u NRD=14 NRS=24 NRG=10
```

Model form

```
.MODEL <model name> NMOS [model parameters]
.MODEL <model name> PMOS [model parameters]
```

Description

The MOSFET is modeled as an intrinsic MOSFET using ohmic resistances in series with drain, source, gate, and bulk (substrate). There is also a shunt resistance (R_{DS}) in parallel with the drain-source channel.



Modeling of EMI Source in PWM Motor Drives

